

Structured Electronic Design

Amplifiers: small-signal dynamic behavior

Linear time-invariant dynamic systems

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Modeling with linear differential equations with constant coefficients

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Sum of a number
of derivatives of
the response

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Sum of a number
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the excitation

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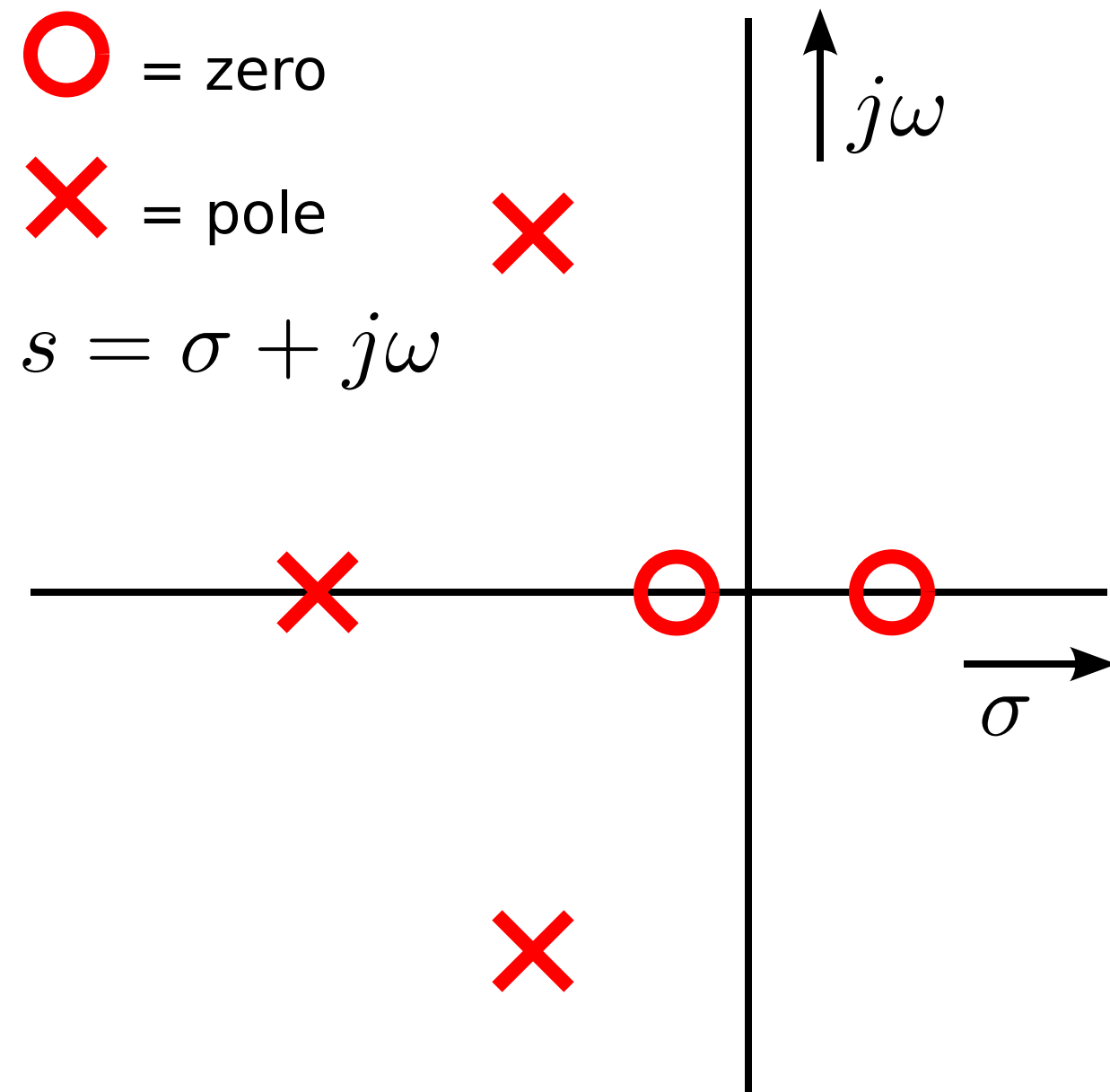
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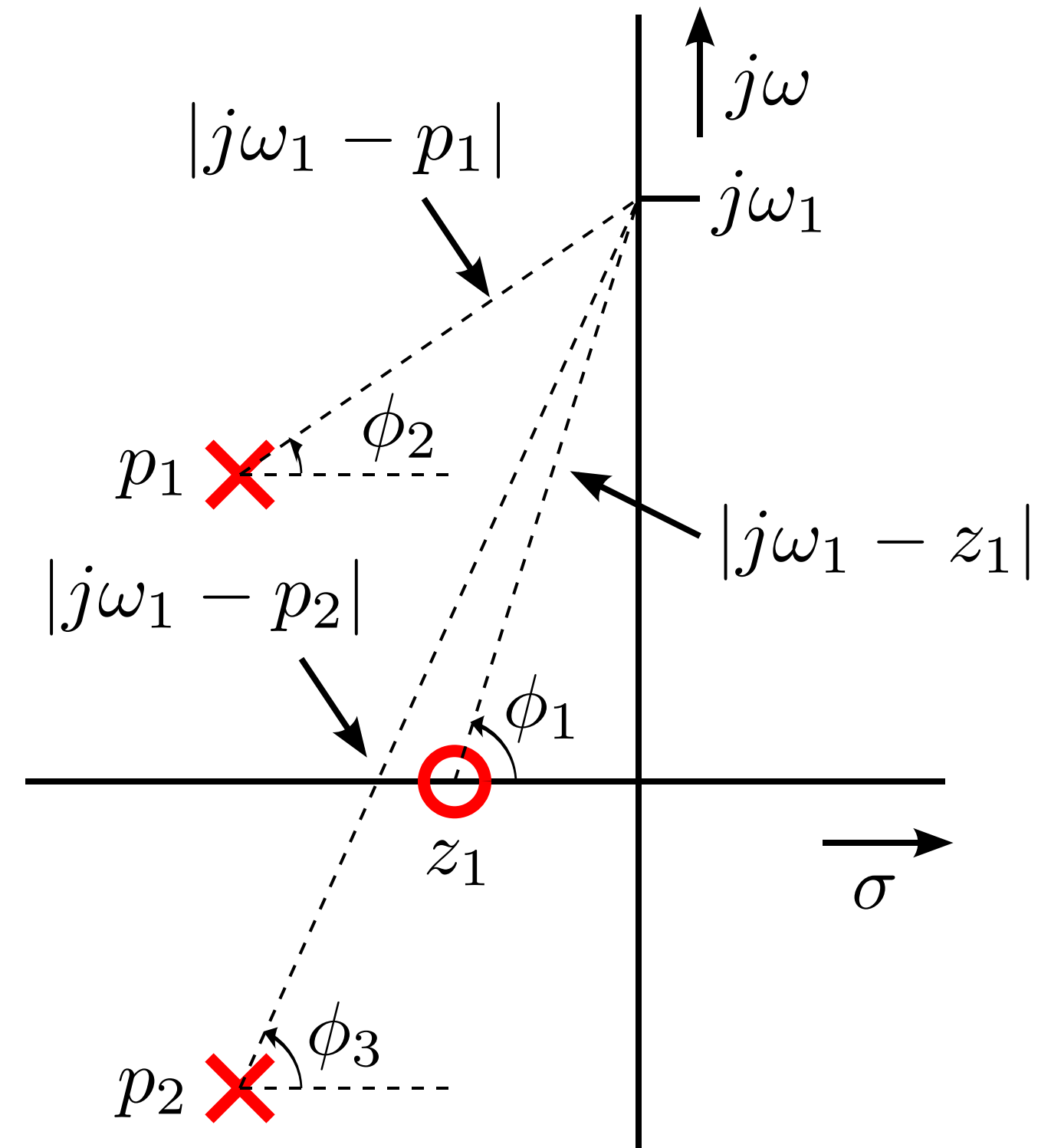
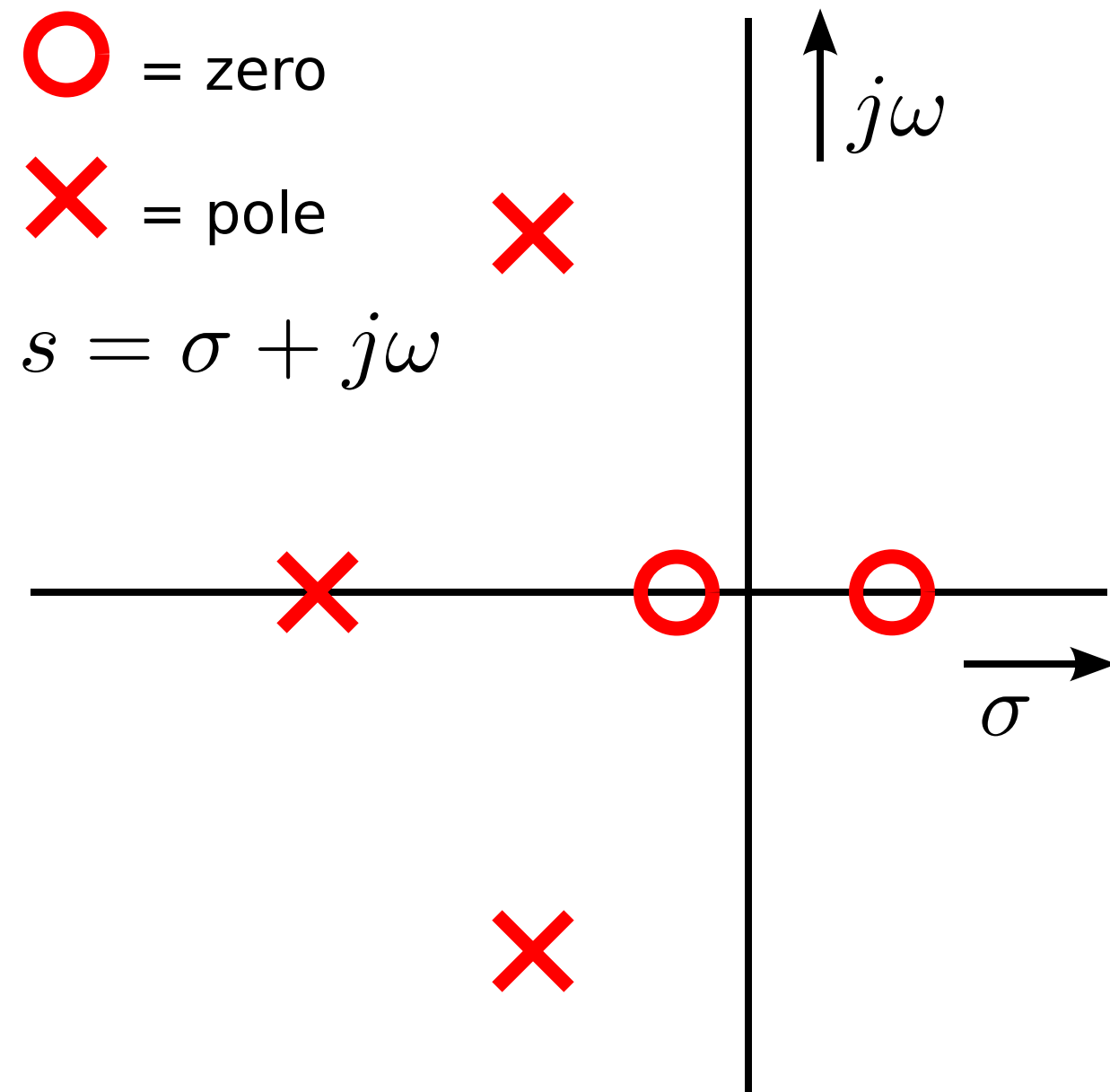
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Pole-zero plots

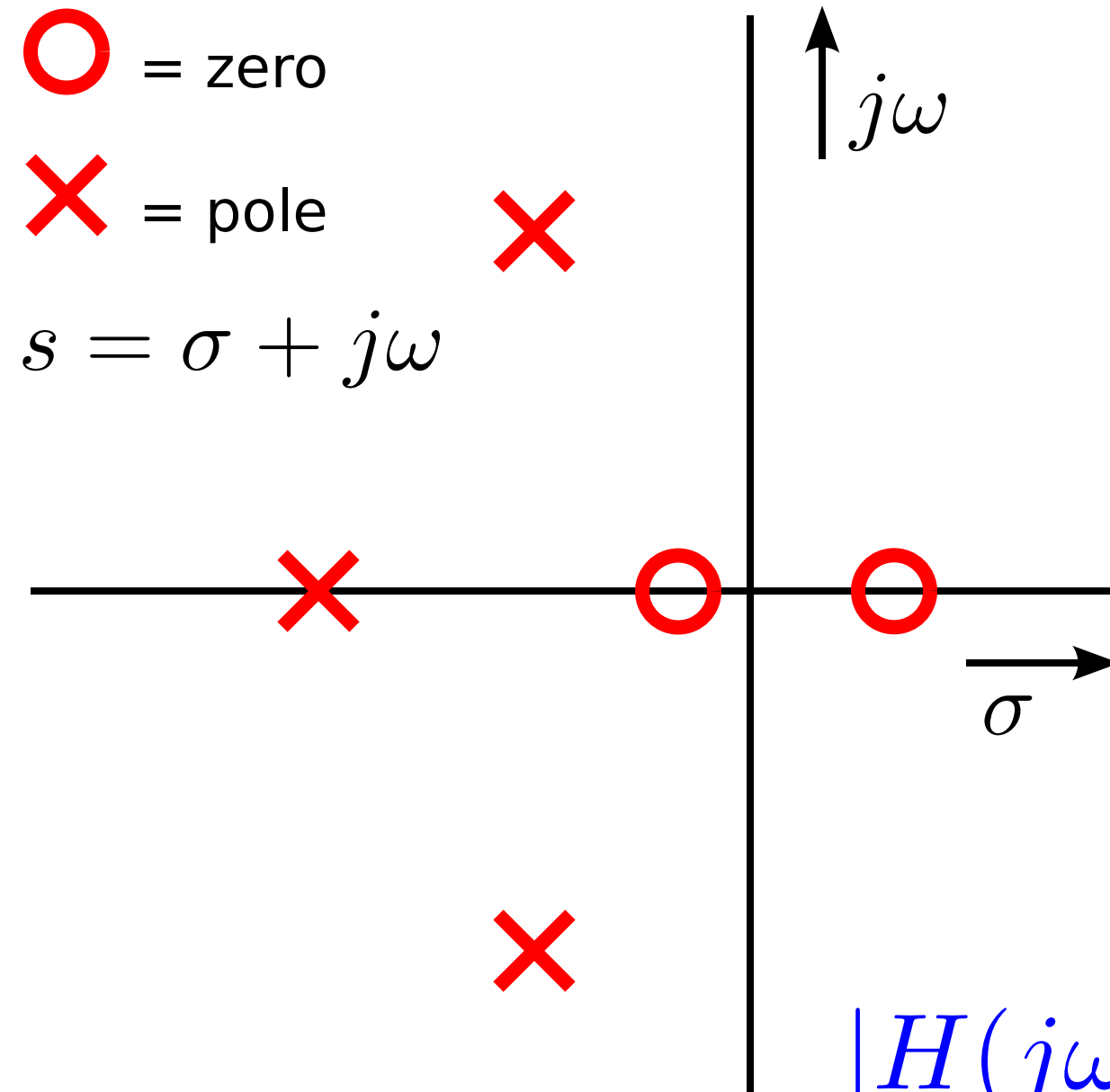
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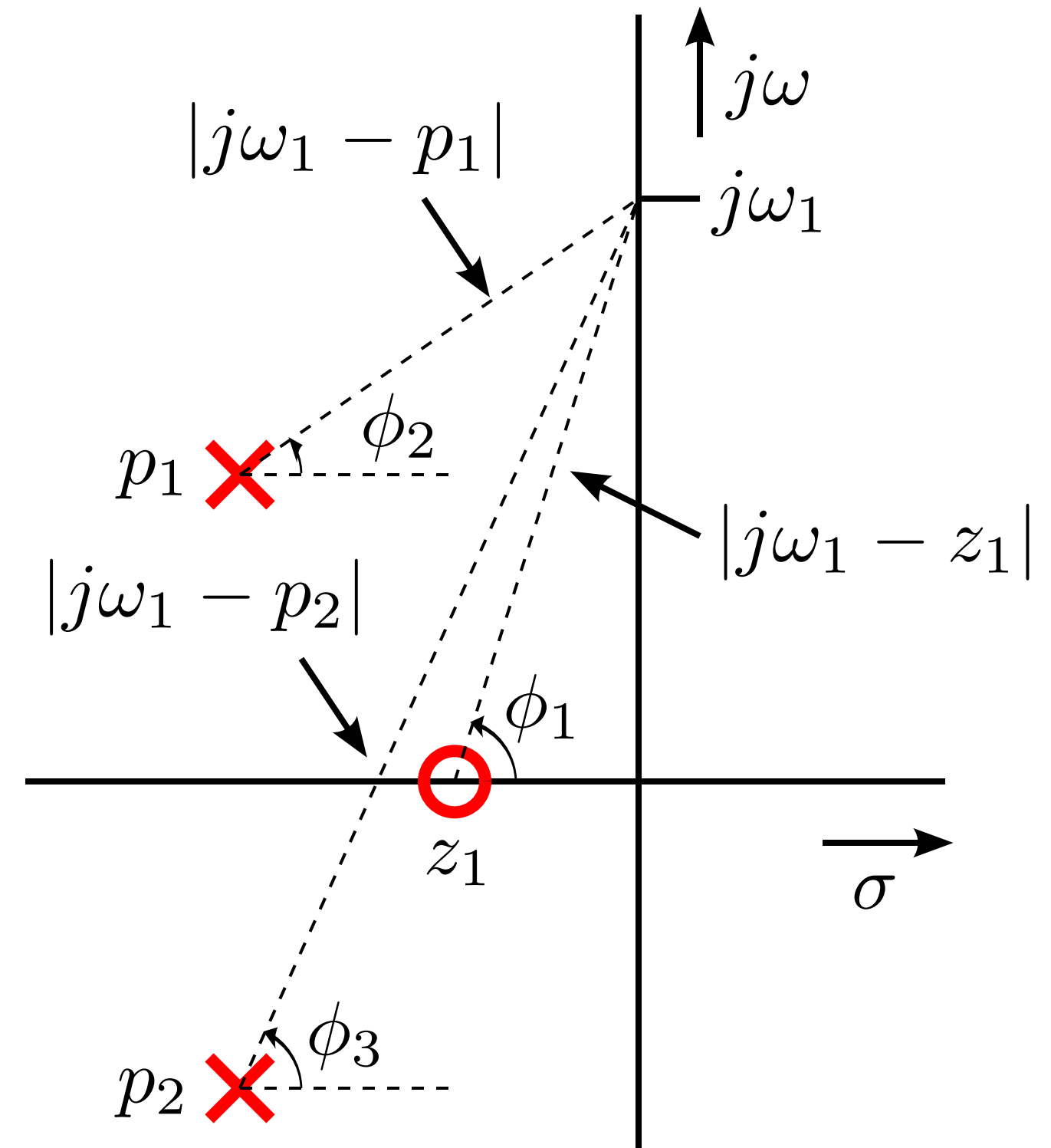
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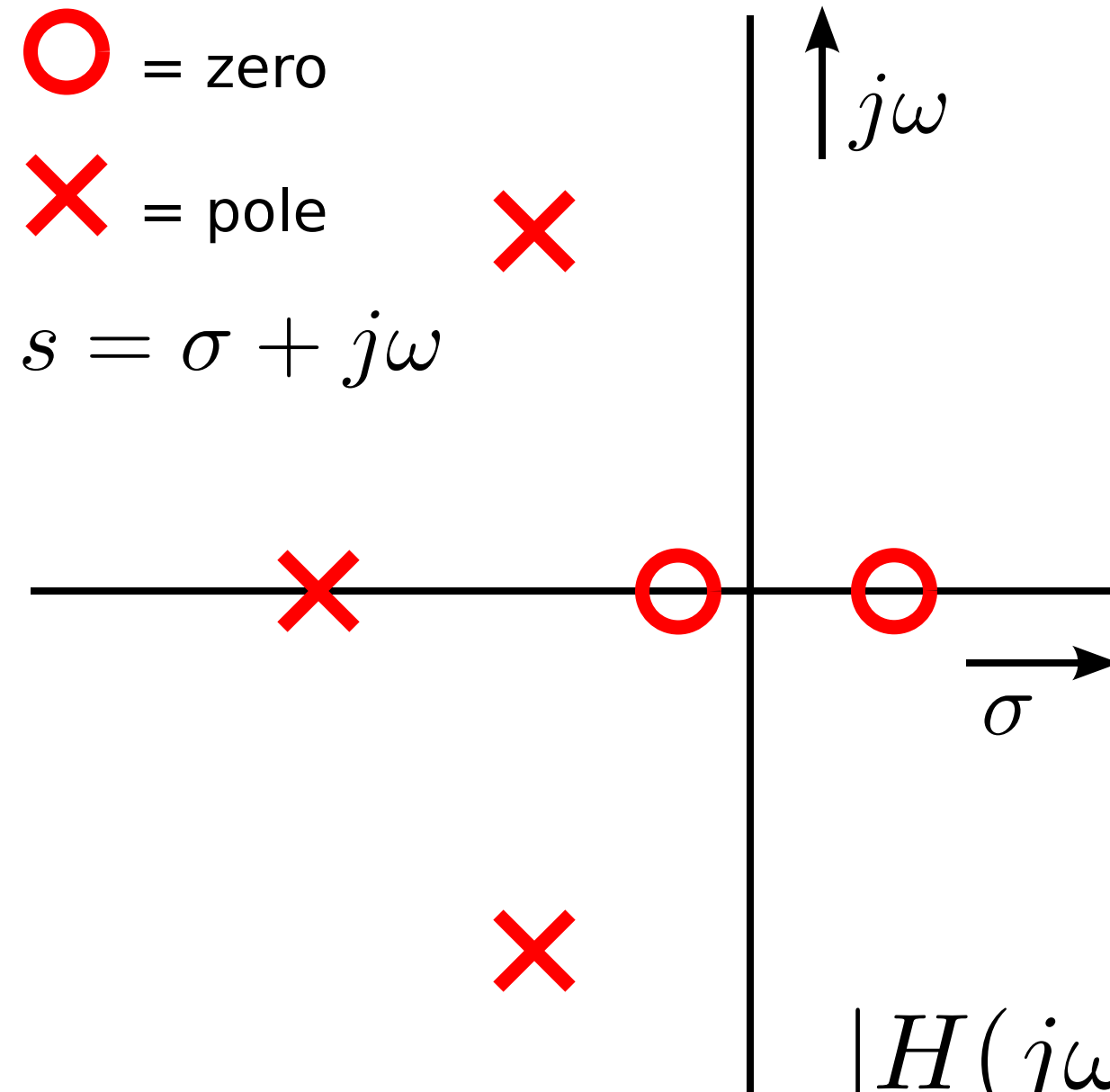
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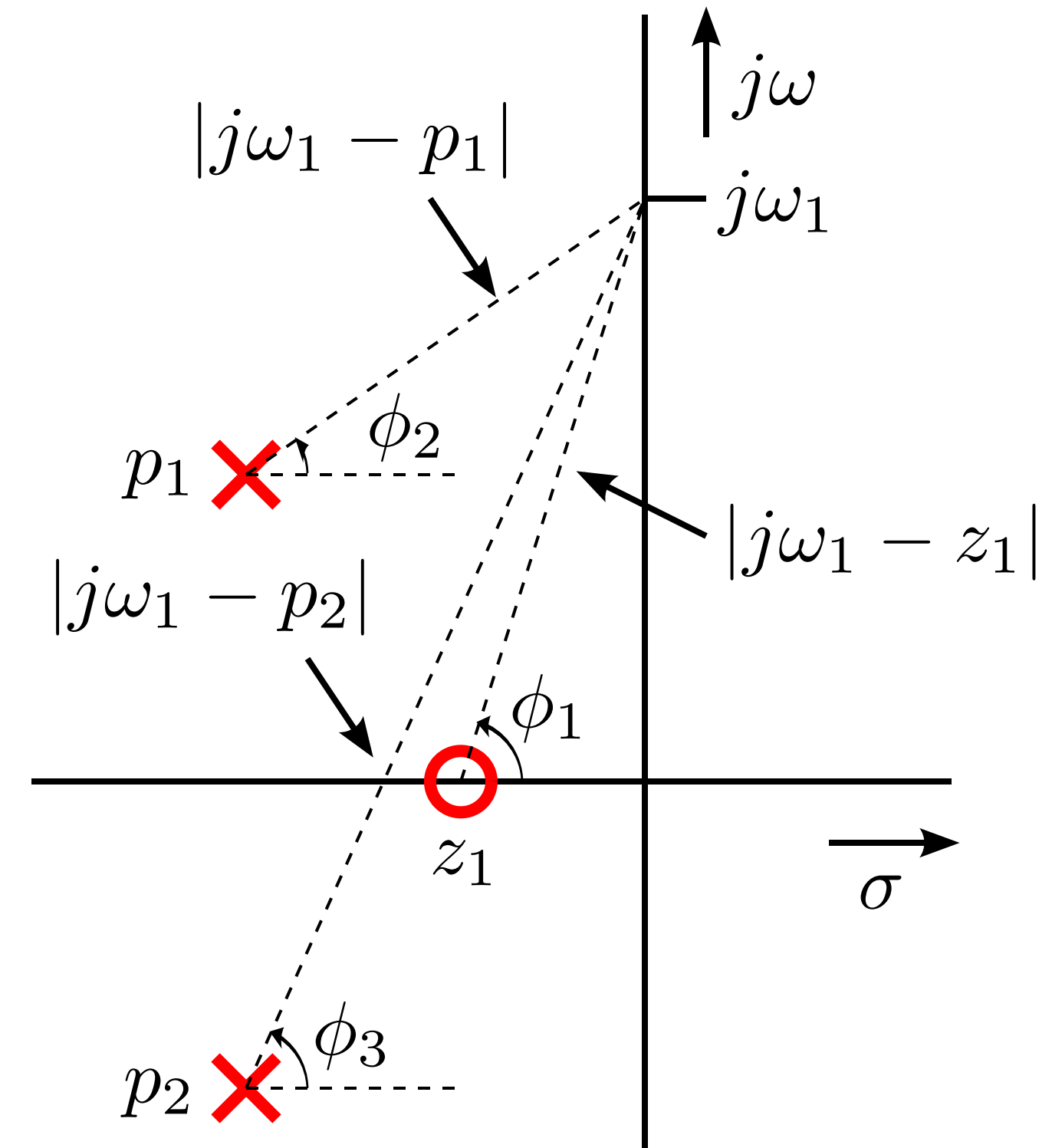
$$|H(j\omega)| = \frac{b_m}{a_n} \frac{\prod_{k=0}^{k=m} |j\omega - z_k|}{\prod_{i=0}^{i=n} |j\omega - p_i|}$$



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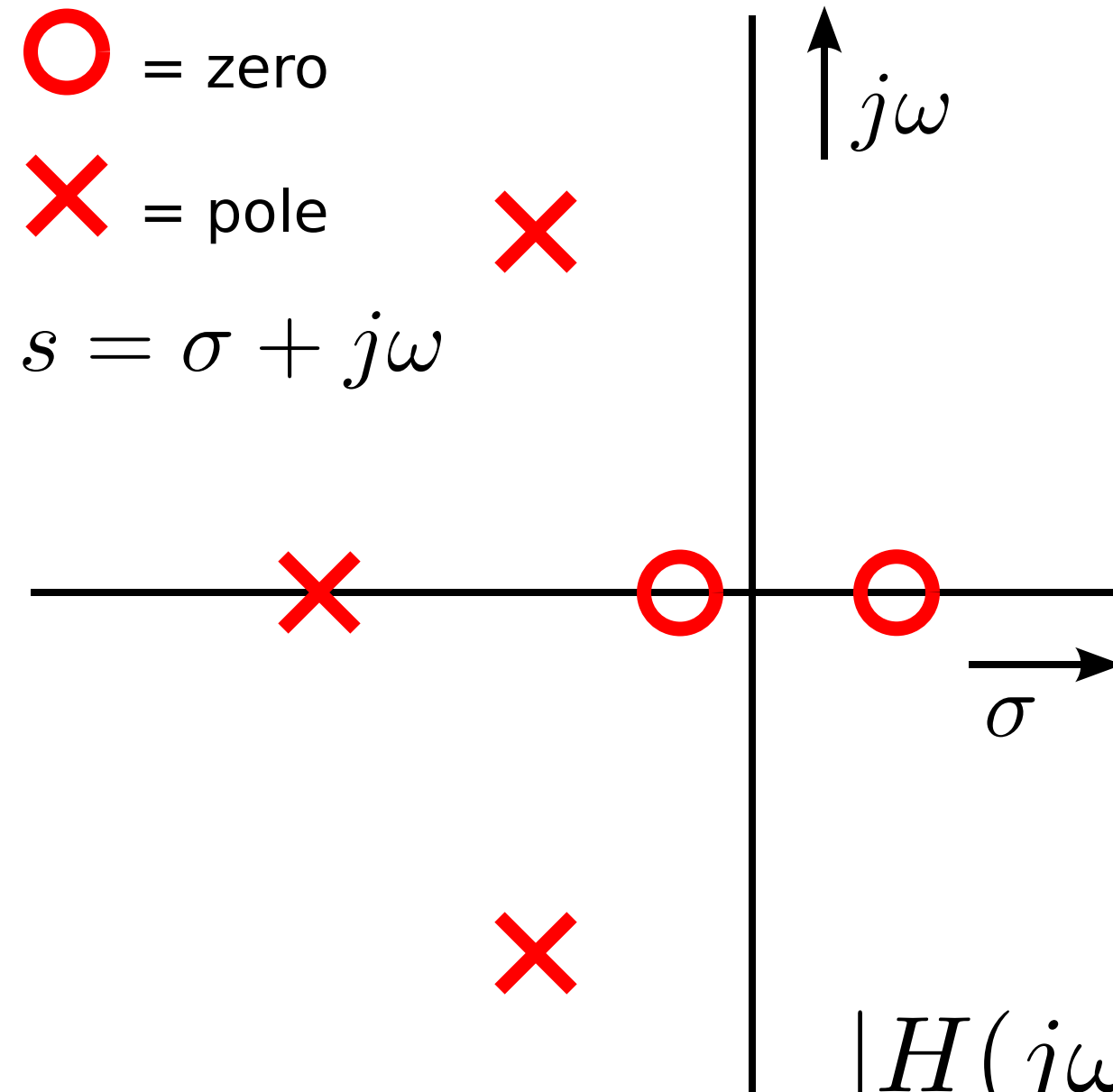


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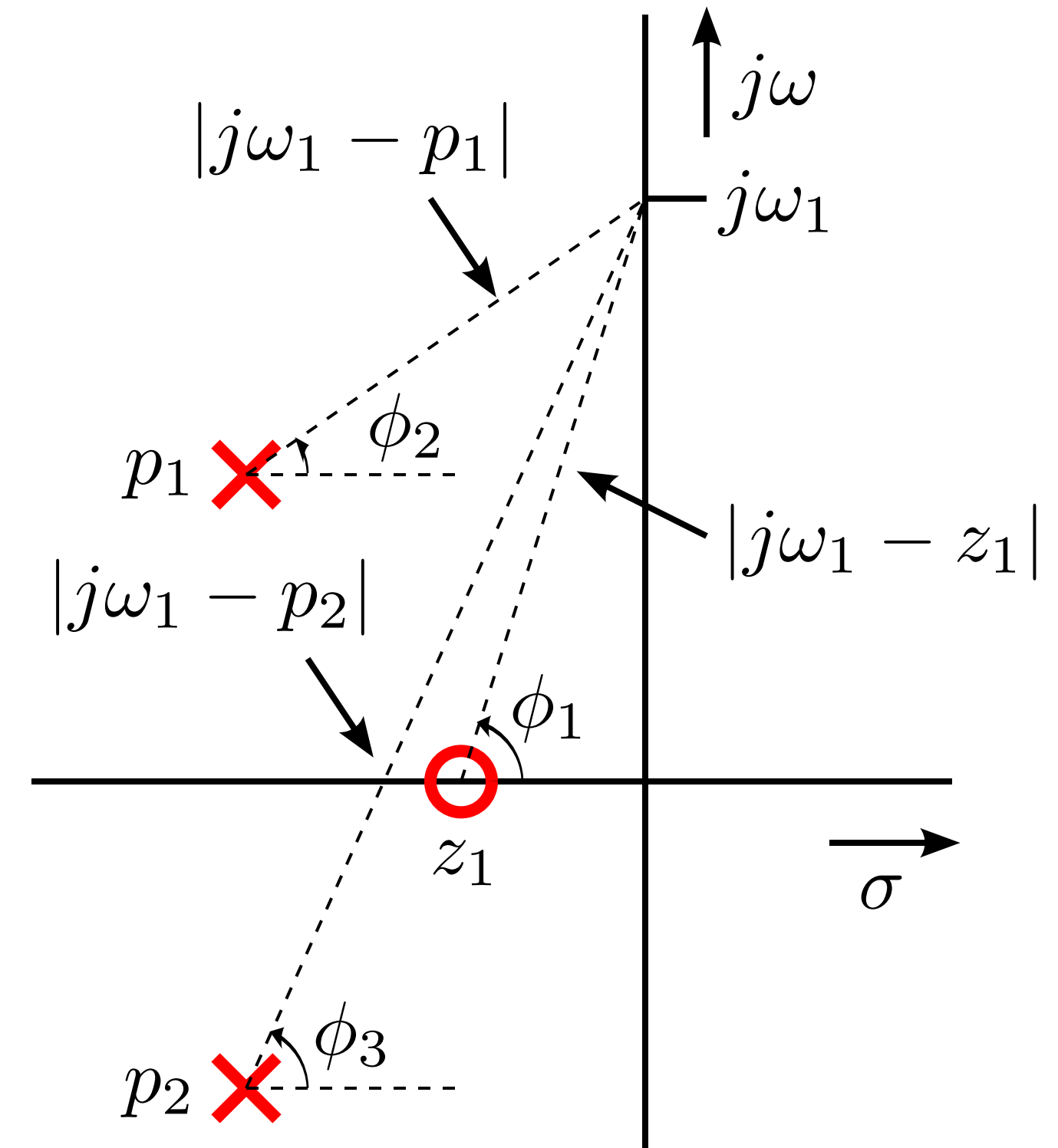


$$\arg\{H(j\omega)\} = \arg b_m - \arg a_n + \sum_{k=0}^{k=m} \arg(j\omega - z_k) - \sum_{i=0}^{i=n} \arg(j\omega - p_i)$$

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Unit impulse response

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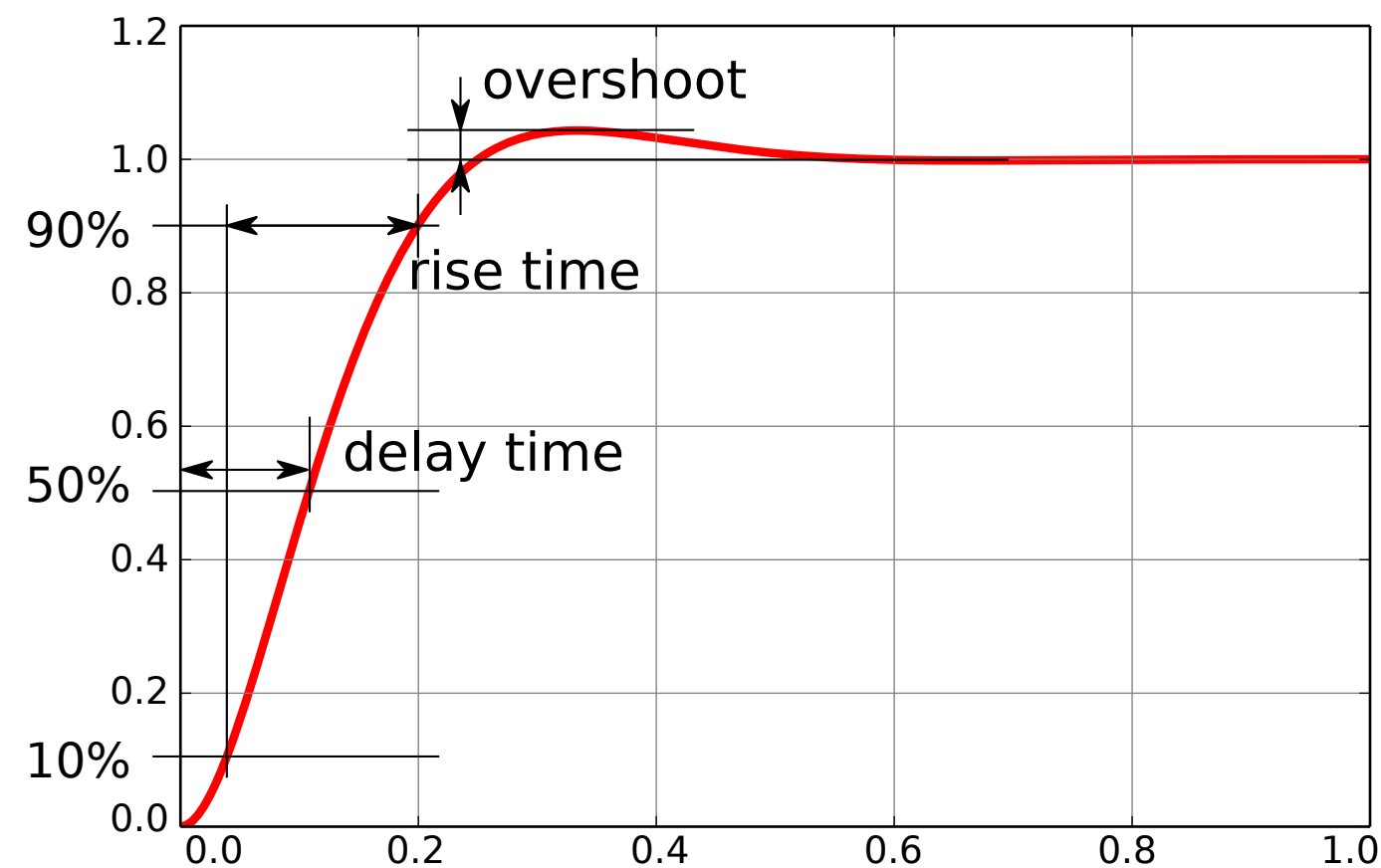
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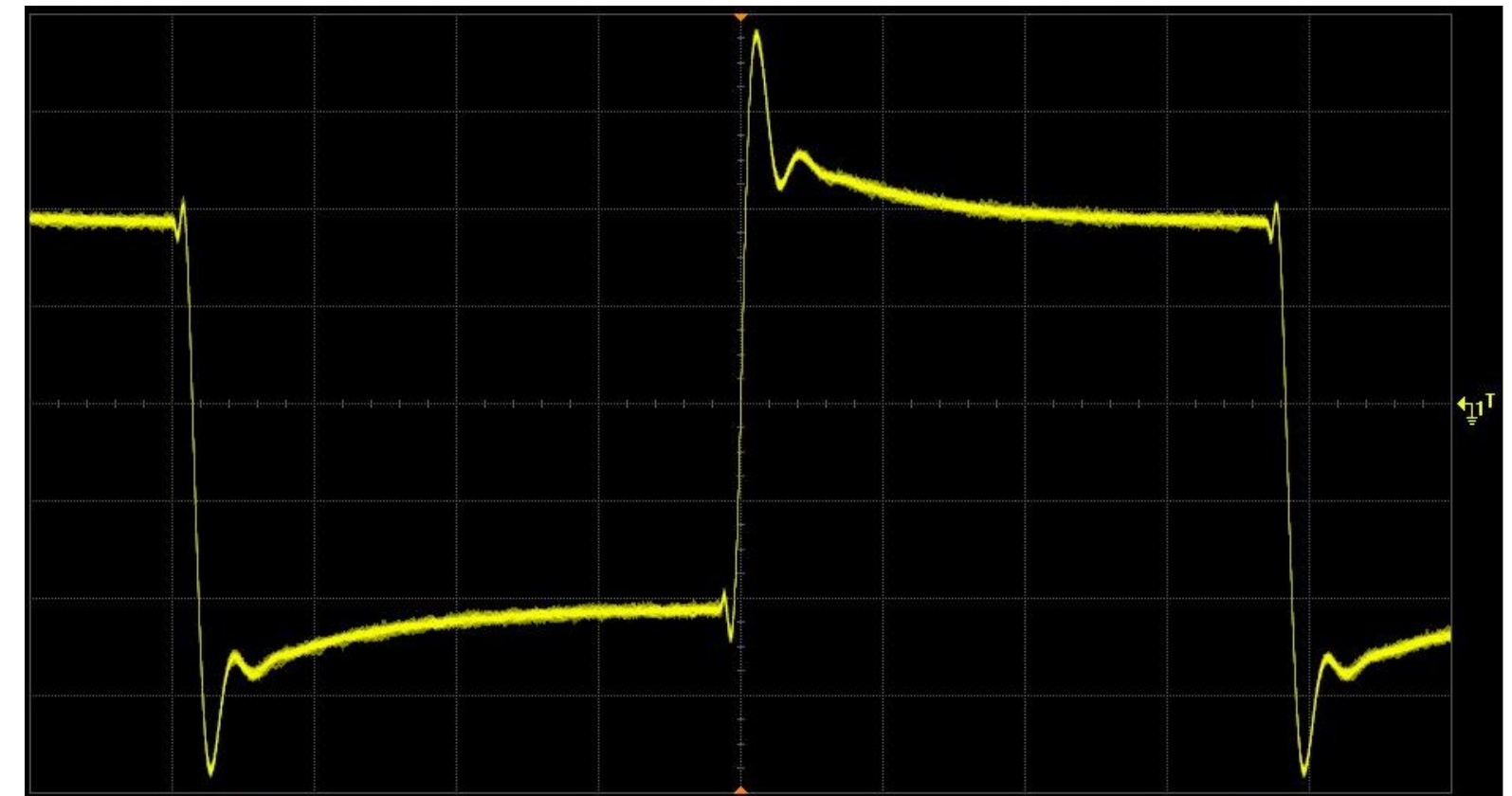
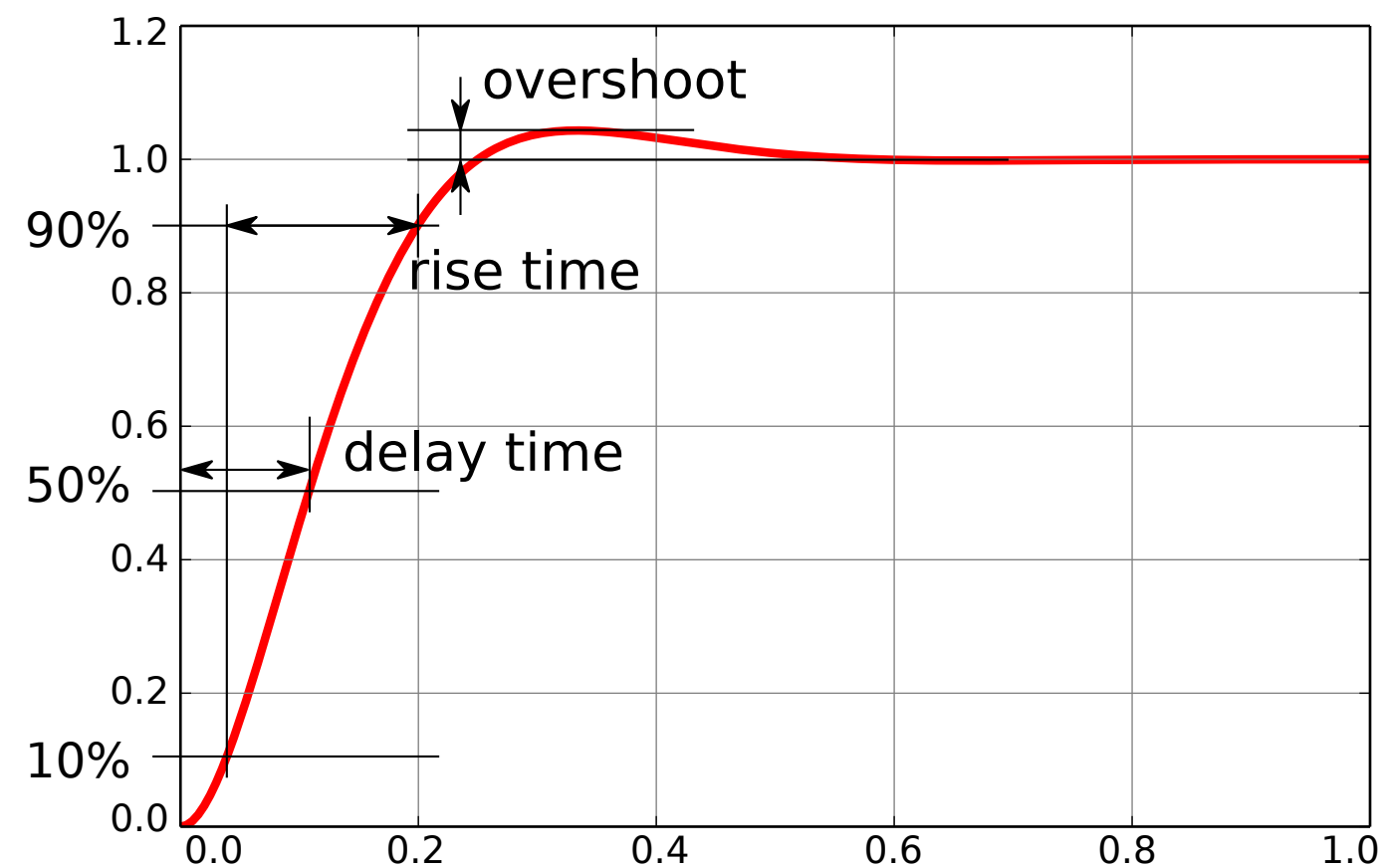
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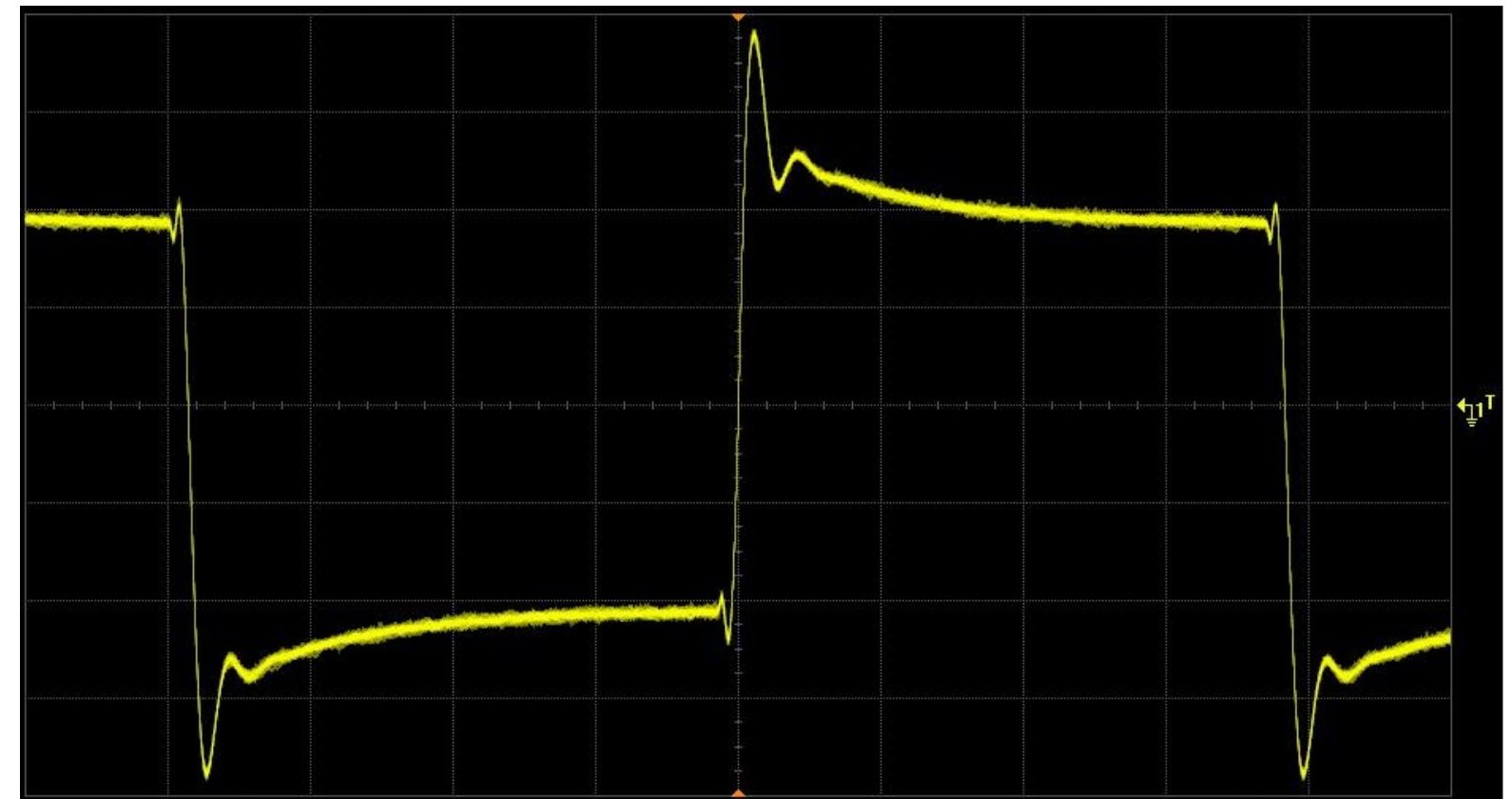
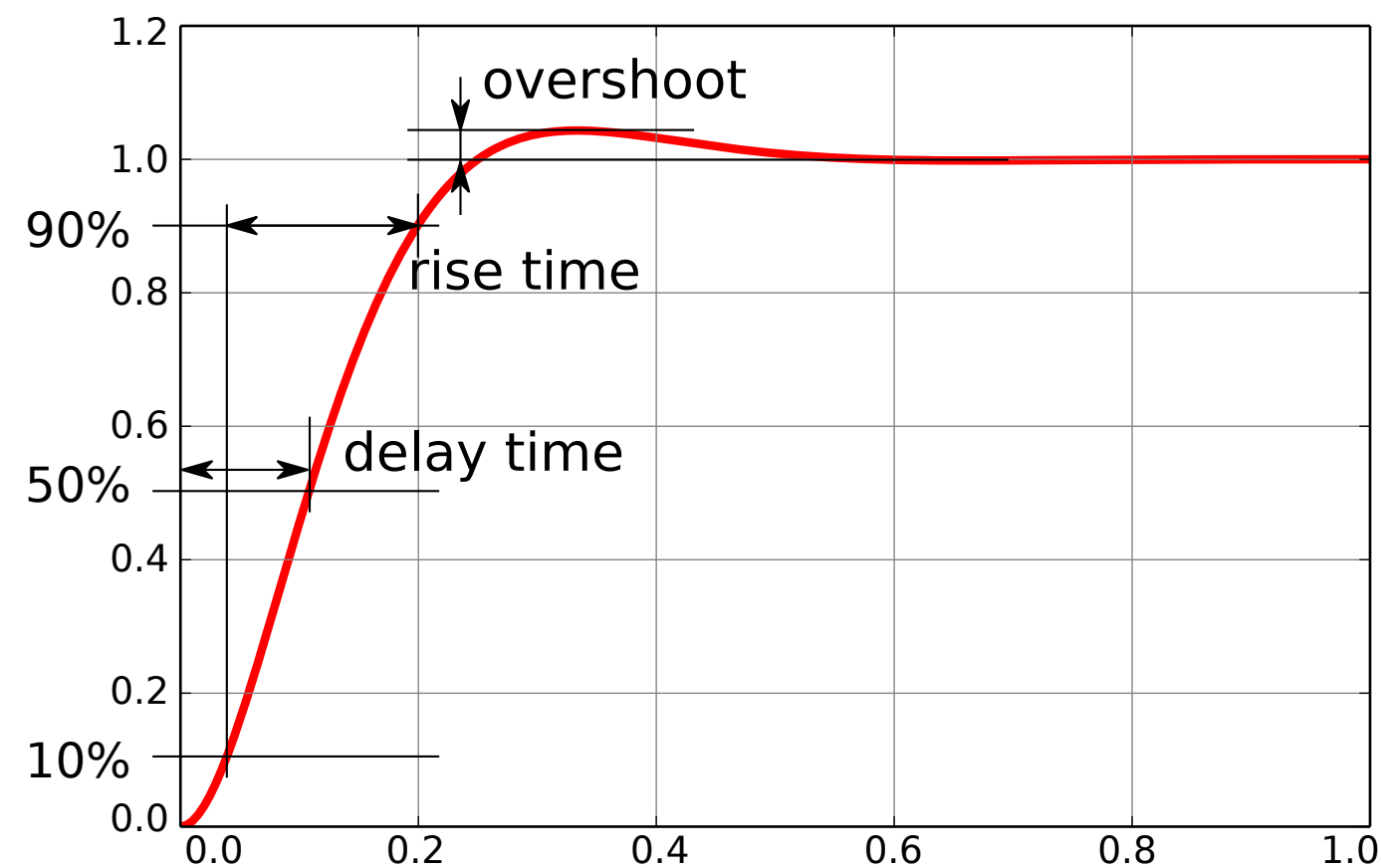
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ℓ : number of occurrences of p_i

$A_{i,k}$: real constant

stable: $\text{Re}(p_i) < 0 \forall i$



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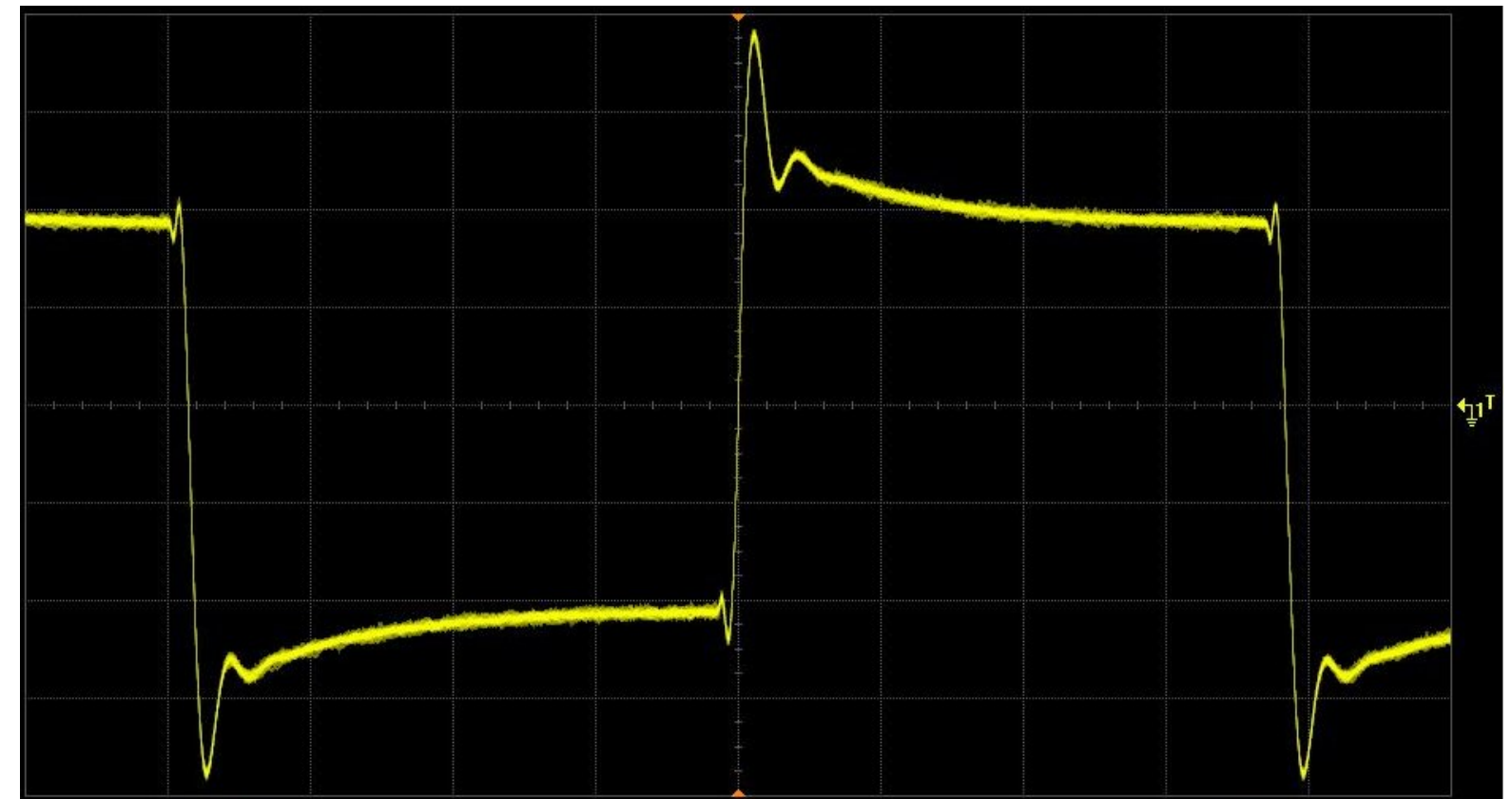
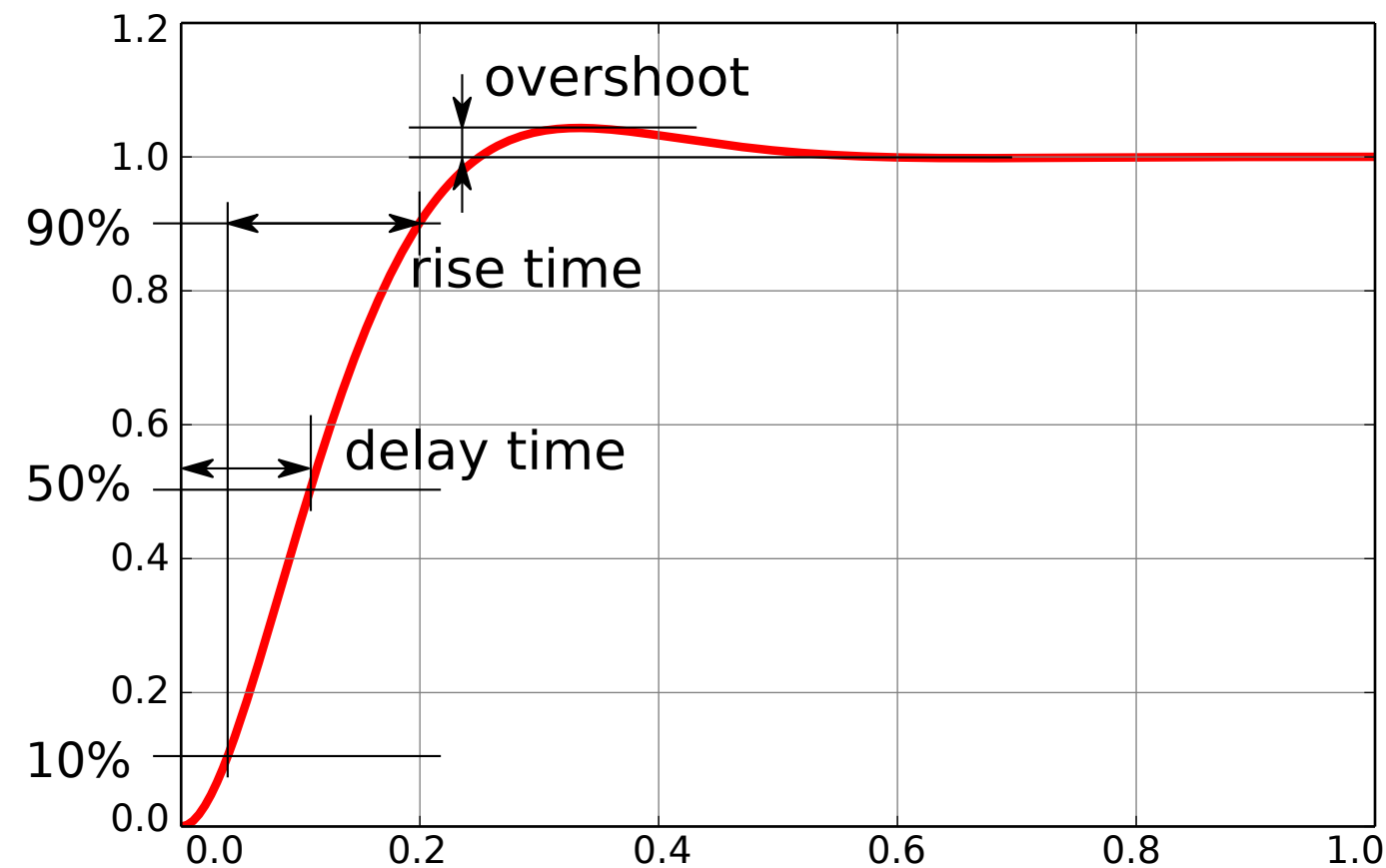
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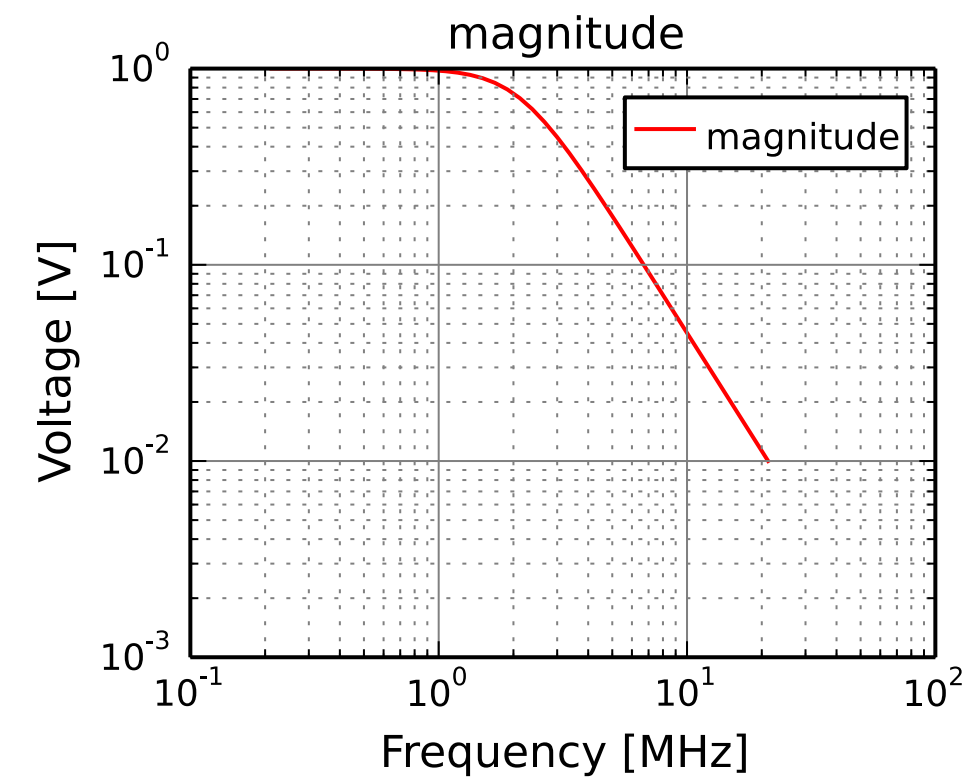
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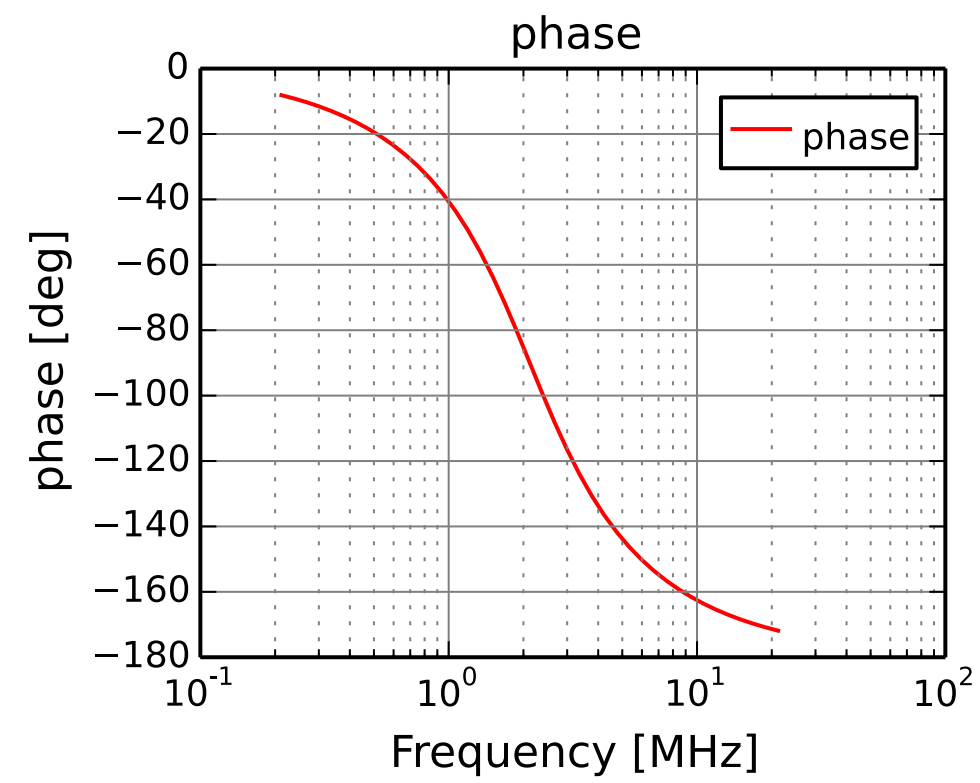
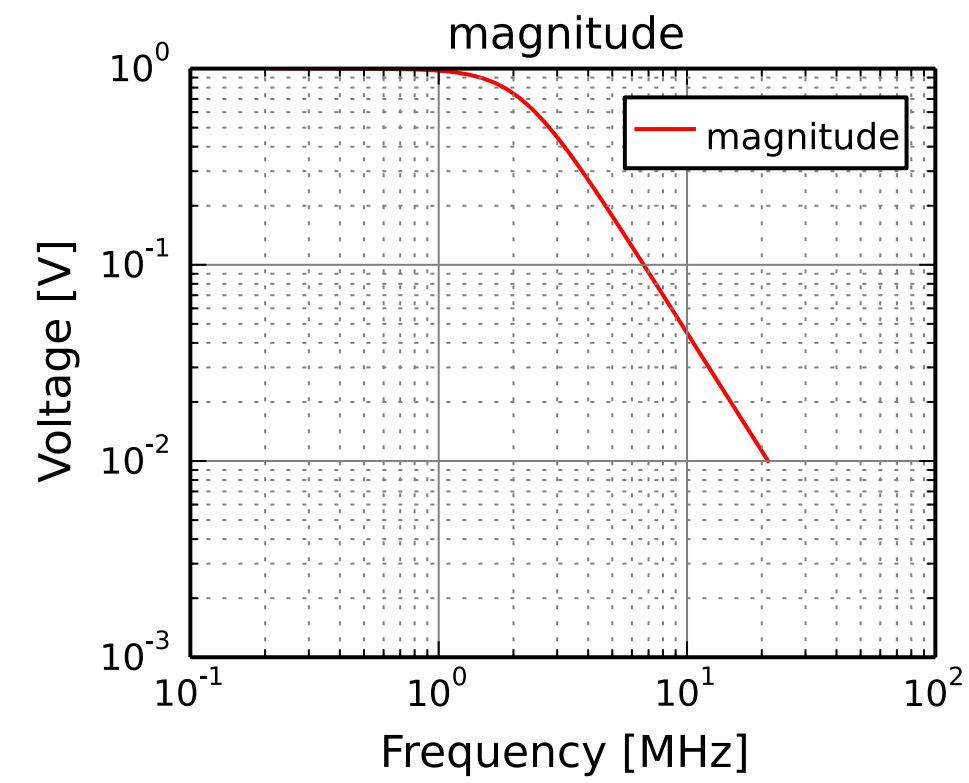


Characterization of LTD systems

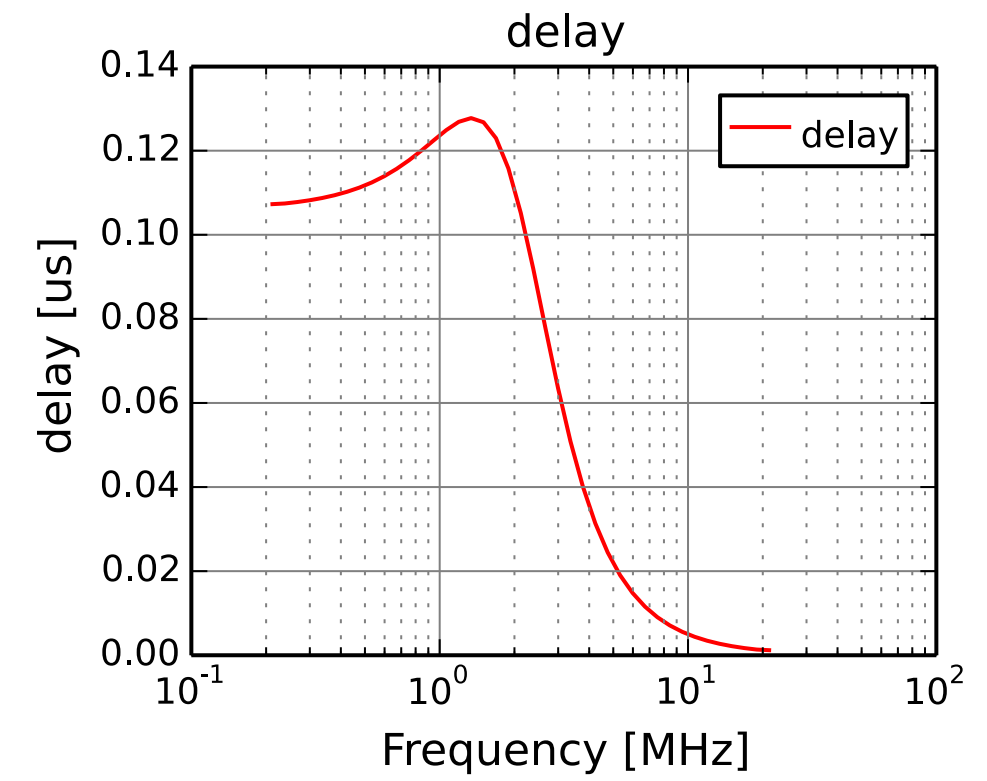
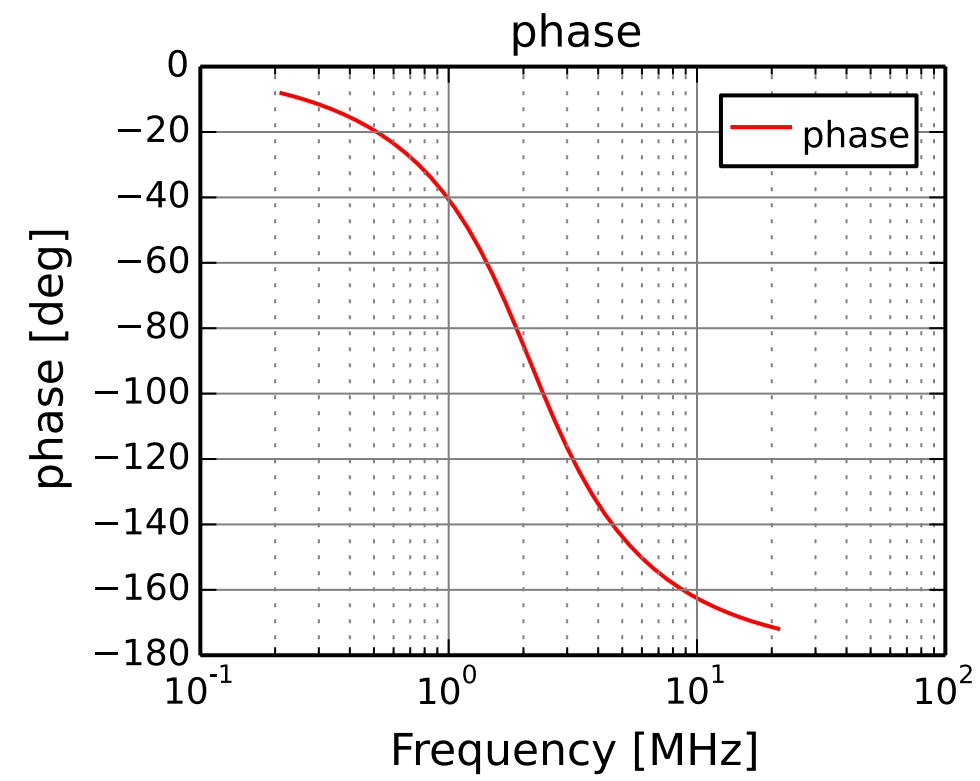
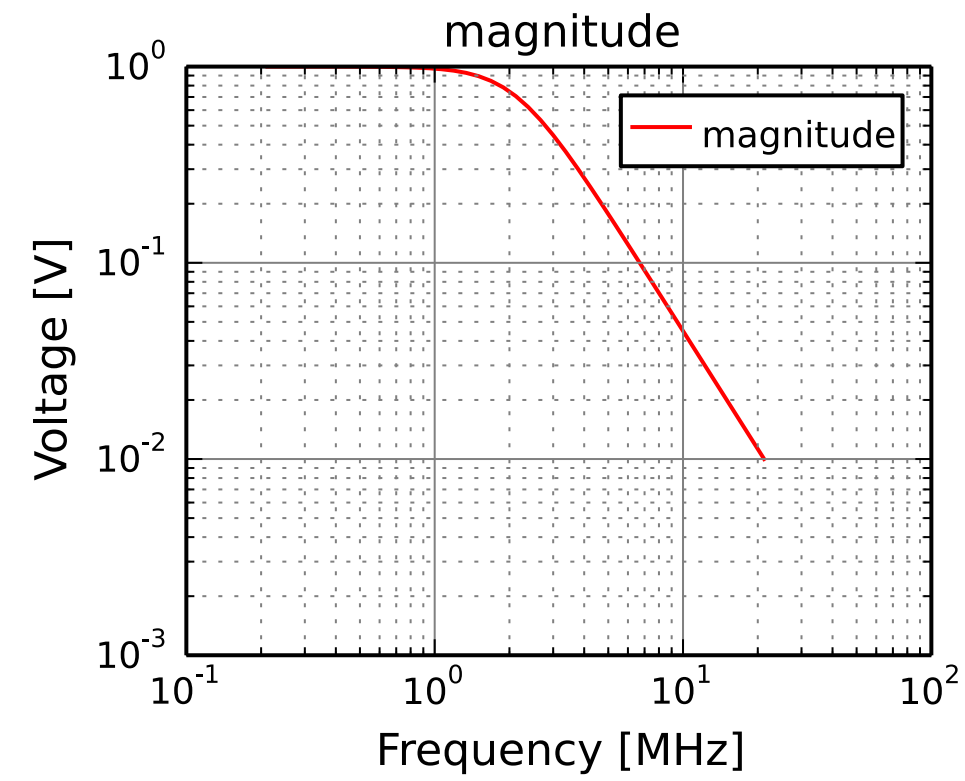
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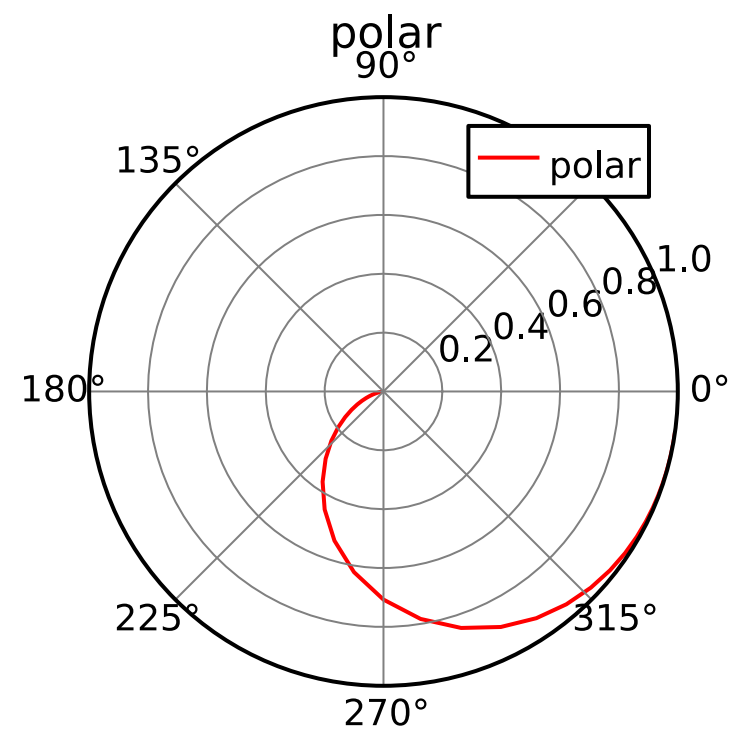
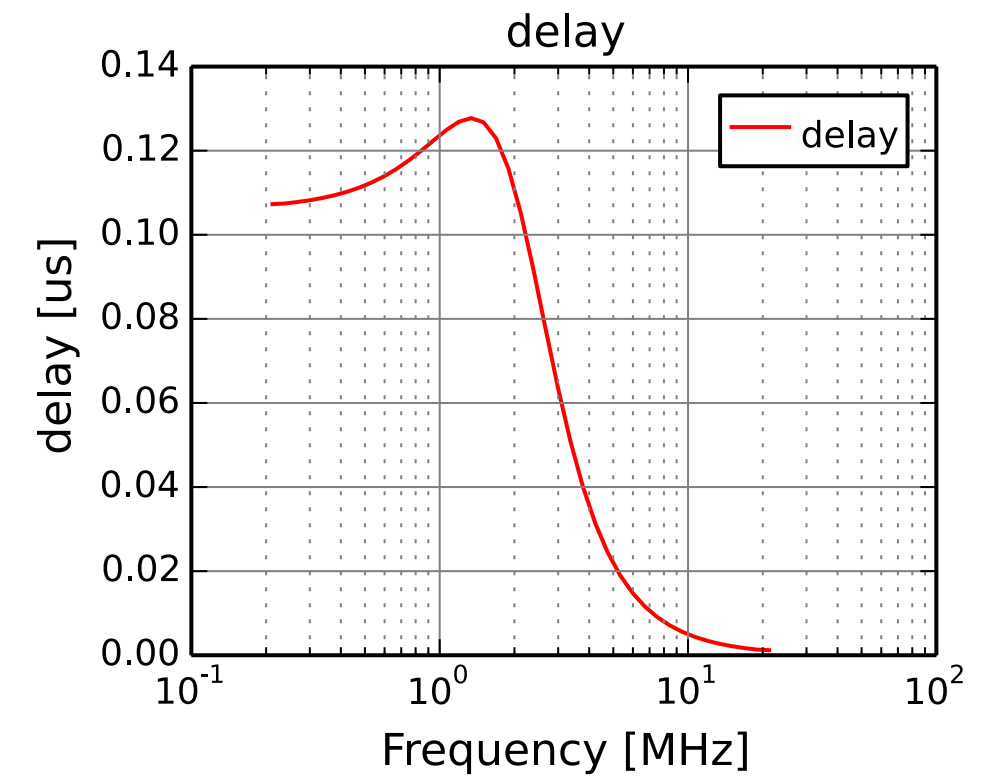
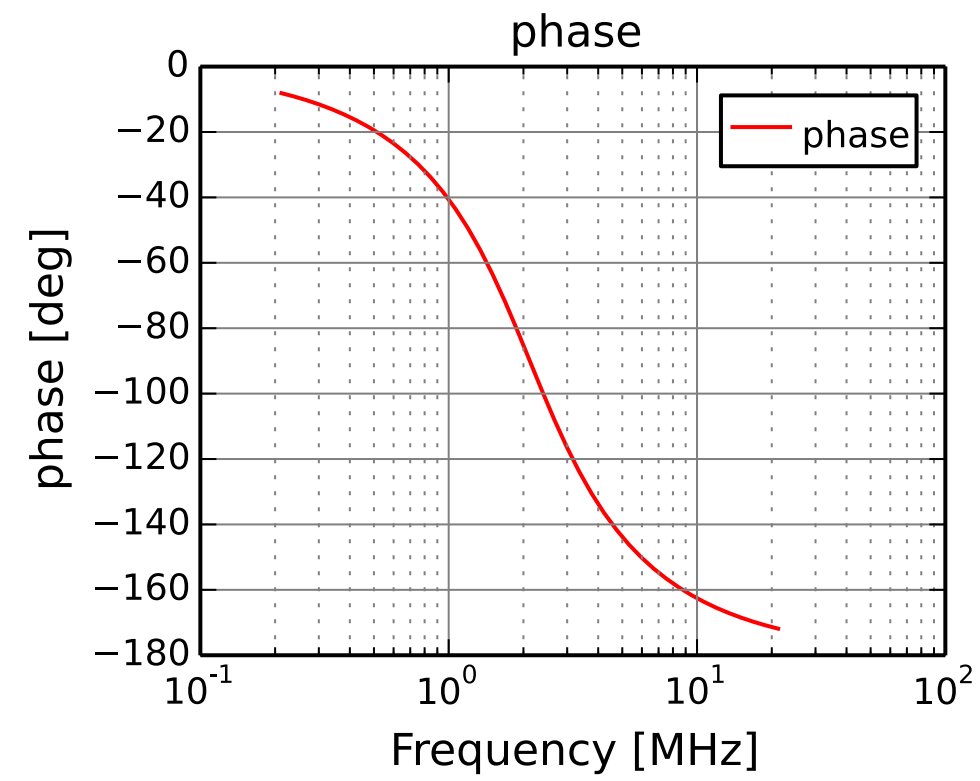
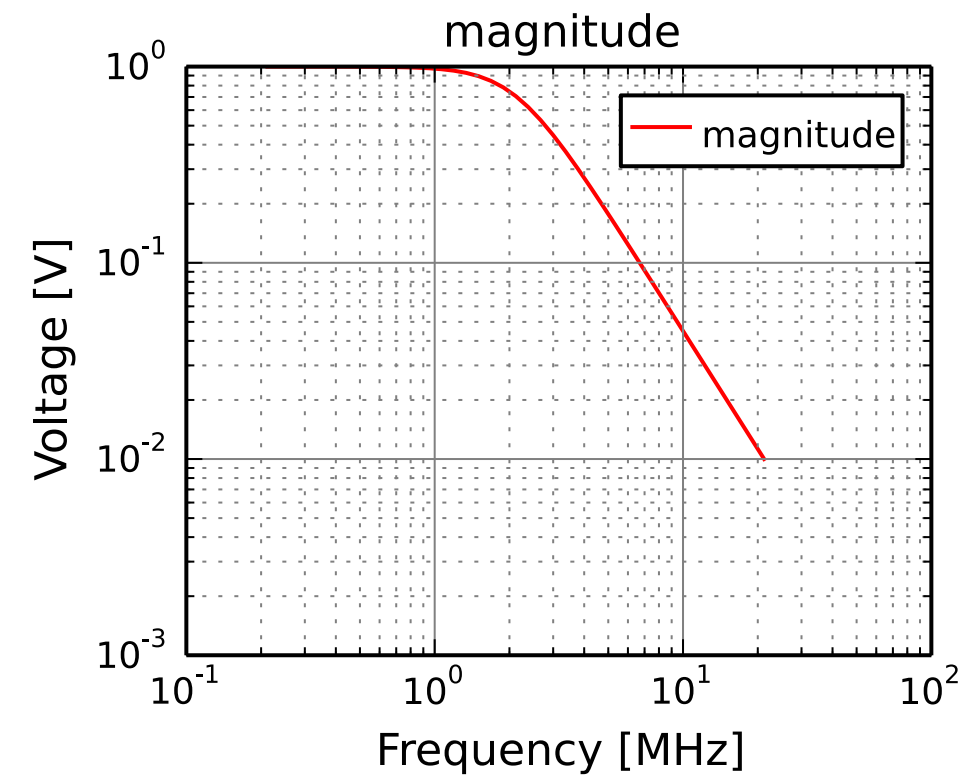
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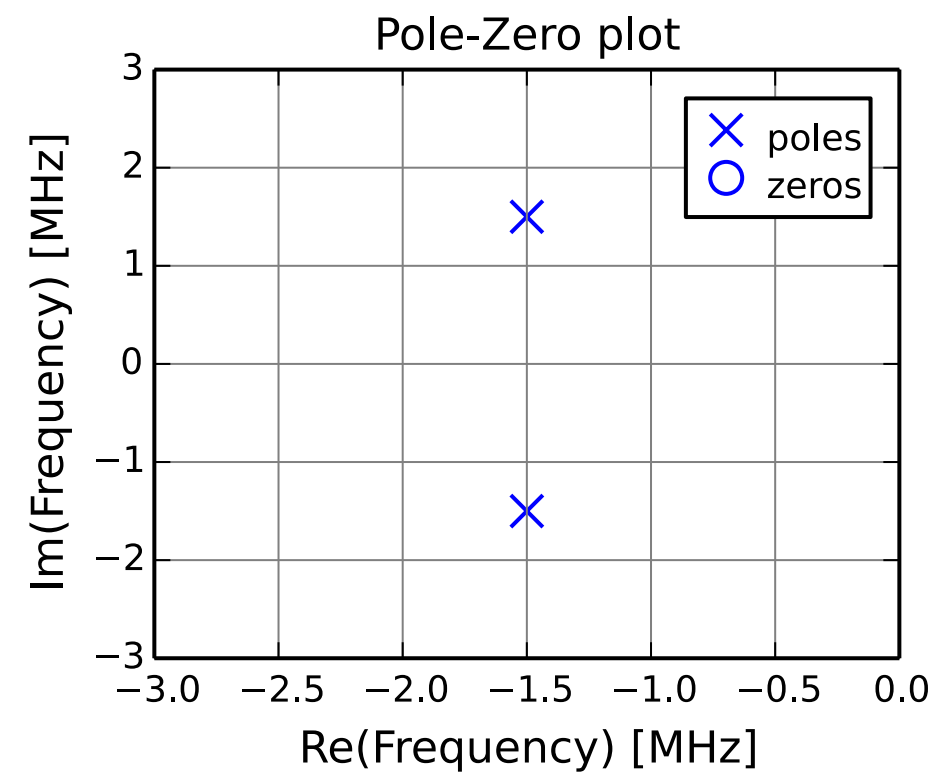
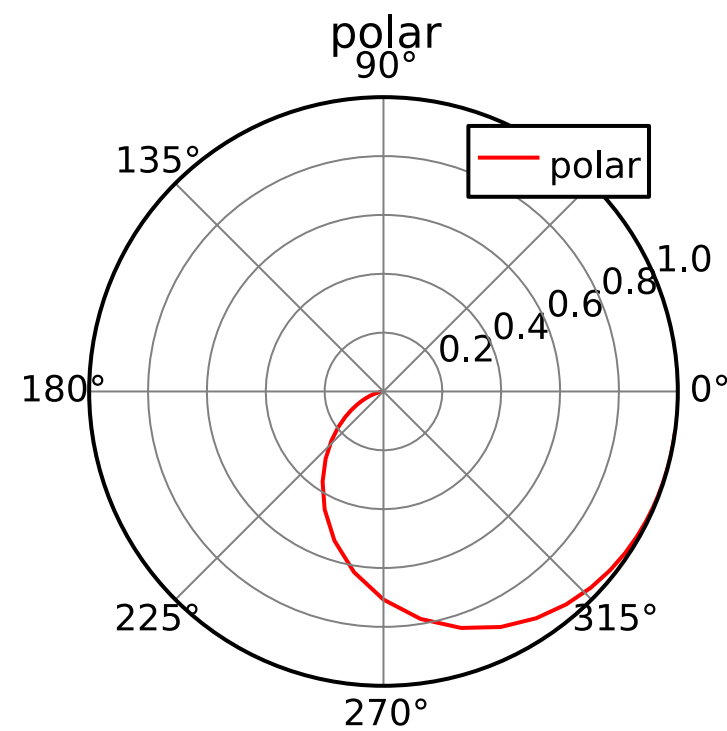
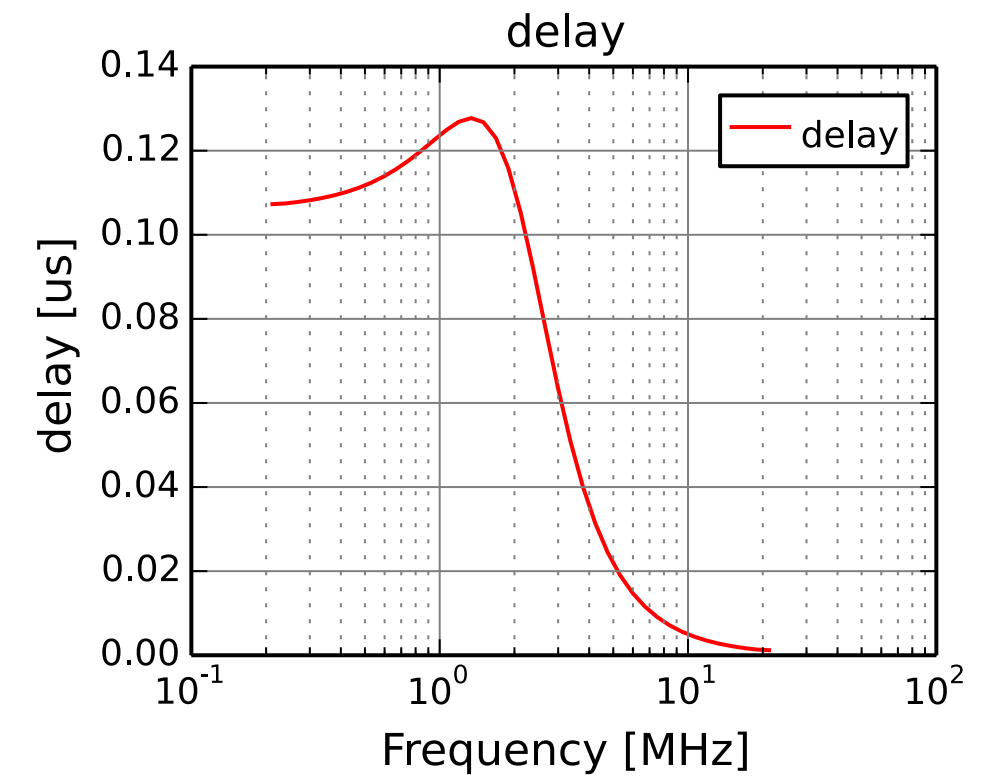
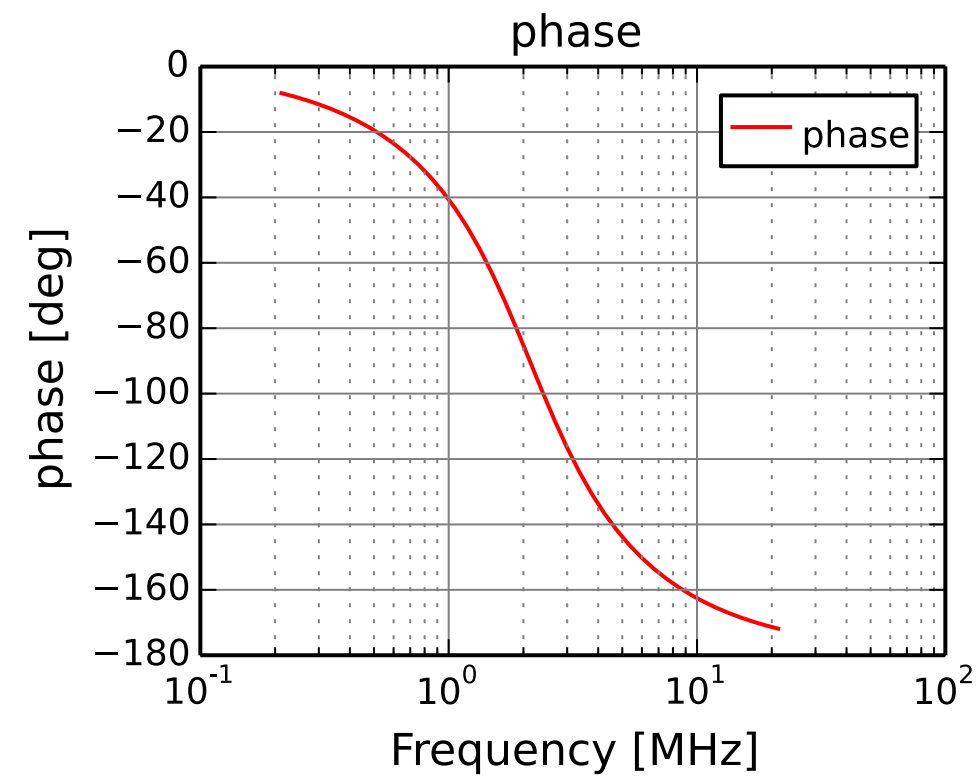
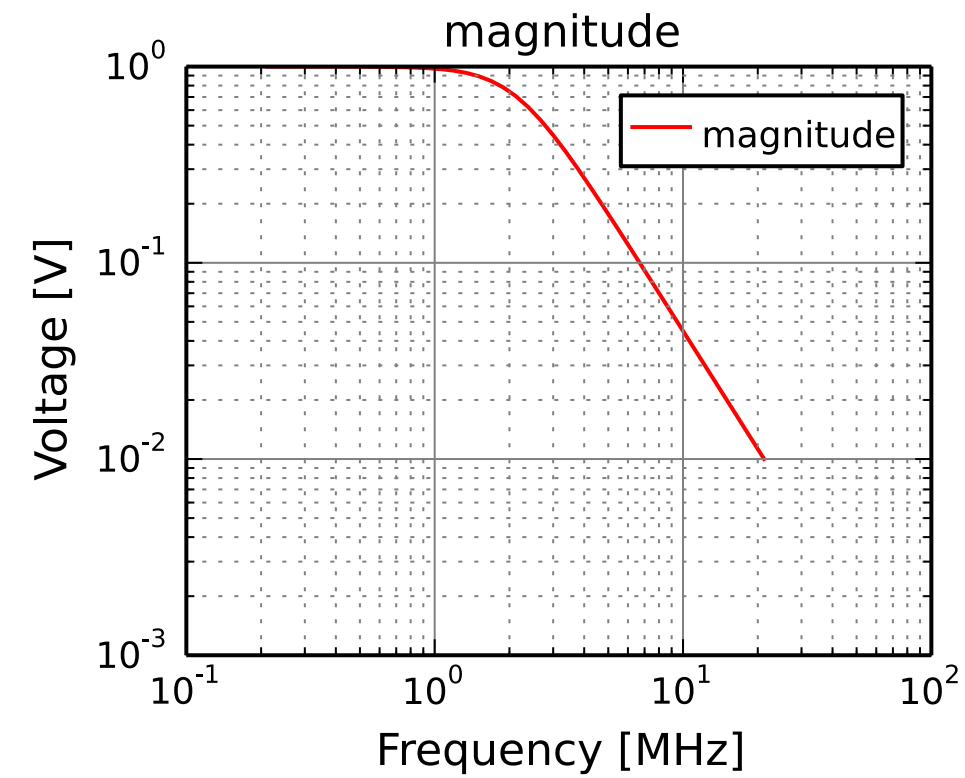
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